

# An elementary definition of globular weak $\infty$ -groupoids

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# Why yet another definition of (weak) $\infty$ -groupoids?

- It's equivalent to Grothendieck's definition (up to some minor changes)
- It's short and simple
- It's an essentially algebraic definition (i.e. an  $\infty$ -groupoid is a globular set equipped with a collection of operations)

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# Outline

- ① Case study: bigroupoids
- ② The definition
- ③ Some examples and properties

# Globular sets

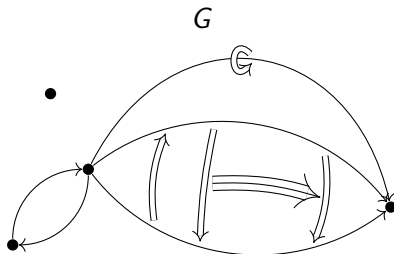
## Proposition

A *globular set*  $G$  has

- a set of *objects*  $\text{Ob}(G)$

$$a : G \stackrel{\text{def}}{\iff} a \in \text{Ob}(G)$$

- for all  $a, b : G$ , a globular set of *morphisms*  $\text{Hom}_G(a, b)$



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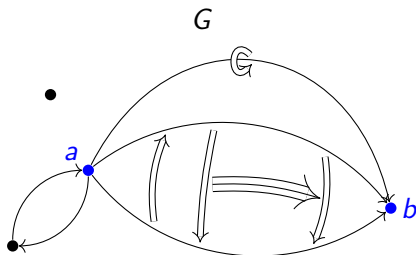
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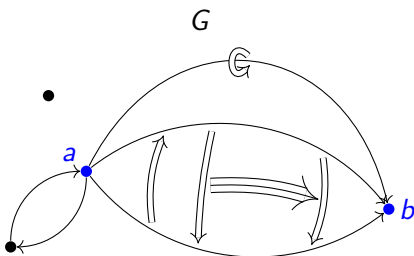
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$$\begin{array}{lcl}
 \begin{array}{c} x \\ \bullet \end{array} & \mapsto & 1_x : \text{Hom}_G(x, x) \\
 \begin{array}{c} x \quad f \quad y \\ \bullet \longrightarrow \bullet \end{array} & \mapsto & f^{-1} : \text{Hom}_G(y, x) \\
 \begin{array}{c} x \quad f \quad y \quad g \quad z \\ \bullet \longrightarrow \bullet \longrightarrow \bullet \end{array} & \mapsto & g \circ f : \text{Hom}_G(x, z) \\
 \begin{array}{c} x \quad f \quad y \quad g \quad z \quad h \quad d \\ \bullet \longrightarrow \bullet \longrightarrow \bullet \longrightarrow \bullet \end{array} & \mapsto & \alpha_{f,g,h} : \text{Hom}_{\dots}(h \circ (g \circ f), (h \circ g) \circ f) \\
 \begin{array}{c} x \quad f \quad y \\ \bullet \longrightarrow \bullet \end{array} & \mapsto & \lambda_f : \text{Hom}_{\text{Hom}_G(x,y)}(1_y \circ f, f) \\
 \begin{array}{c} x \quad f \quad y \\ \bullet \longrightarrow \bullet \end{array} & \mapsto & \rho_f : \text{Hom}_{\text{Hom}_G(x,y)}(f \circ 1_x, f)
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$$\begin{array}{c} f \\ \text{---} \\ \text{---} \\ \alpha \\ \text{---} \\ g \end{array} \quad \begin{array}{c} x \\ \bullet \end{array} \begin{array}{c} \curvearrowright \\ \curvearrowleft \end{array} \begin{array}{c} y \\ \bullet \end{array} \quad \mapsto \quad i(\alpha) : \text{Hom}_{\text{Hom}_G(y,x)}(f^{-1}, g^{-1})$$

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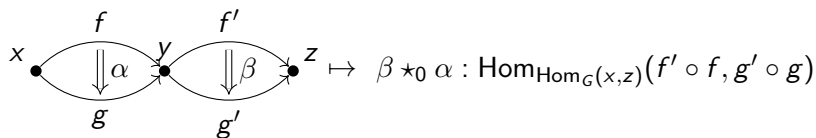
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$$\begin{array}{c} x \\ \bullet \end{array} \begin{array}{c} \xrightarrow{f} \\ \Downarrow \alpha \\ \xrightarrow{g} \end{array} \begin{array}{c} y \\ \bullet \end{array} \begin{array}{c} \xrightarrow{f'} \\ \Downarrow \beta \\ \xrightarrow{g'} \end{array} \begin{array}{c} z \\ \bullet \end{array} \quad \mapsto \quad \beta \star_0 \alpha : \text{Hom}_{\text{Hom}_G(x,z)}(f' \circ f, g' \circ g)$$

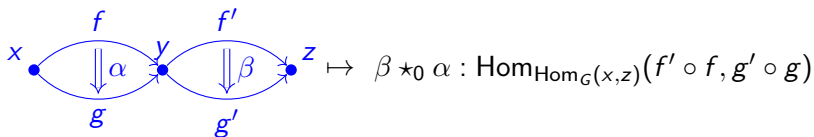
$$\begin{array}{c} \begin{array}{c} \xrightarrow{f} \\ \Downarrow \alpha \\ \xrightarrow{g} \end{array} \\ \begin{array}{c} x \\ \bullet \end{array} \xrightarrow{h} \begin{array}{c} y \\ \bullet \end{array} \\ \begin{array}{c} \xrightarrow{f} \\ \Downarrow \beta \\ \xrightarrow{h} \end{array} \end{array} \quad \mapsto \quad \beta \star_1 \alpha : \text{Hom}_{\text{Hom}_G(x,y)}(f, h)$$

## Anatomy of an operation



Every operation has two parts:

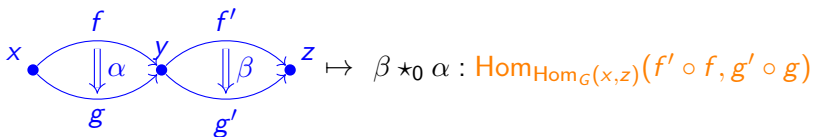
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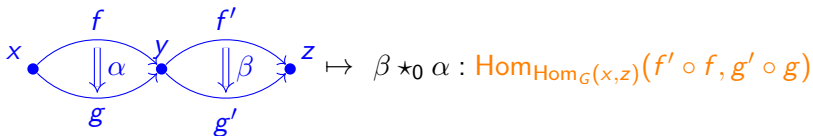


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- The **input**: is a bunch of variables with a “contractible” shape
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  - the variables in the input
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## Anatomy of an operation



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  - possibly some other operations of the structure of  $\infty$ -groupoid

Conversely, any contractible **input** and well-formed **output** should correspond to some operation of  $\infty$ -groupoids.

# Idea

Define a *syntax* in which we can express the notion of

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Define a *syntax* in which we can express the notion of

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Two basic syntactic notions:

- **types**  
→ represent iterated hom globular sets of  $G$
- **terms**  
→ represent cells of  $G$

Every term has an associated type. We write:

$$u : A \xleftrightarrow{\text{def}} \text{the term } u \text{ has type } A$$

# Contexts

In a term like  $g \circ f$ , we need to know what  $f$  and  $g$  are.

→ types and terms are considered in a given *context*

context = list of variables you are allowed to use

## Definition

A **context** is a sequence  $\Gamma = (x_1 : A_1, \dots, x_n : A_n)$  of variables and types such that:

- the variables  $x_i$  are pairwise distinct
- for every  $k \in \{1, \dots, n\}$ ,  $A_k$  is a type in the context  $(x_1 : A_1, \dots, x_{k-1} : A_{k-1})$

# Types

## Definition

In a context  $\Gamma$ , a **type** is either:

- the base type (which corresponds to  $G$ ):

$$\star$$

- a hom type (which corresponds to  $\text{Hom}_A(u, v)$ ):

$$u \simeq_A v$$

In the last case we require that

- $A$  is a type in  $\Gamma$
- $u$  and  $v$  are terms of type  $A$  in  $\Gamma$

## Context and types (examples)

### Examples (well-formed contexts)

$$(x : \star), (y : \star), (z : \star), (f : x \simeq_{\star} y), (g : y \simeq_{\star} z)$$

and

$$(f : \star), (g : \star)$$

### Counterexamples (ill-formed contexts)

$$(f : x \simeq_{\star} y), (g : y \simeq_{\star} z)$$

and

$$(x : \star), (y : \star), (f : x \simeq_{\star} y), (g : y \simeq_{\star} x), (\alpha : f \simeq_{?} g)$$

# Contractible contexts

## Definition

A context  $\Delta$  is **contractible** if either:

- $\Delta$  is a singleton

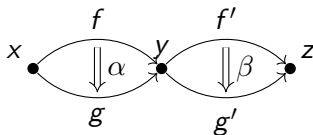
$$\Delta = (x : \star)$$

- $\Delta$  is obtained from some contractible context  $\Delta'$  by duplicating a variable  $(x : A) \in \Delta'$  and “gluing a ball”:

$$\Delta = (\Delta', (y : A), (z : x \simeq_A y))$$

(where  $y$  and  $z$  are fresh variables)

## Contractible contexts (example)

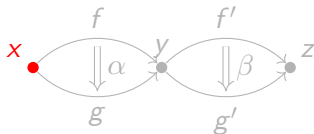


corresponds to

$$\Delta_{\star_0} := ((x : \star), (y : \star), (f : x \simeq_{\star} y), (g : x \simeq_{\star} y), (\alpha : f \simeq_{x \simeq_{\star} y} g), \\ (z : \star), (f' : y \simeq_{\star} z), (g' : y \simeq_{\star} z), (\beta : f' \simeq_{y \simeq_{\star} z} g'))$$



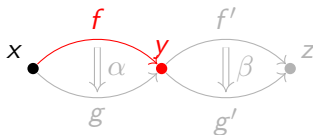
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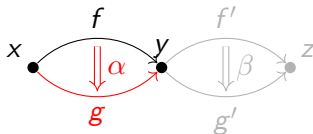
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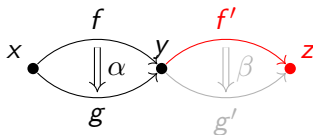
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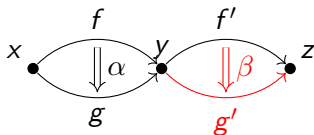
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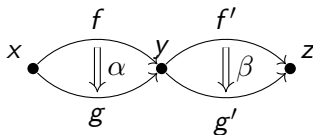
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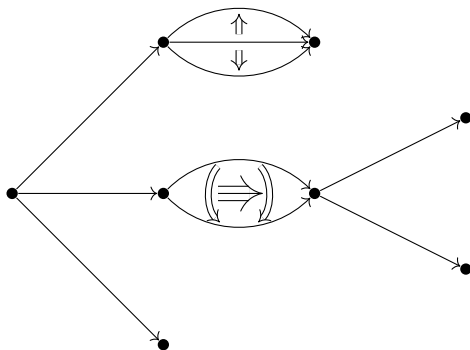
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# Contractible contexts (another example)



# Terms

## Definition

In a context  $\Gamma$ , a **term** is either:

- a variable  $x$  such that  $(x : A) \in \Gamma$  for some  $A$
- a coherence cell

$$\text{coh}_{\Delta.A}(u_1, \dots, u_n)$$

For a coherence cell we require that:

- the **input**  $\Delta = (x_1 : B_1, \dots, x_n : B_n)$  is a contractible context
- the **output**  $A$  is a type in  $\Delta$
- in the context  $\Gamma$ , the arguments  $u_k$  are terms satisfying

$$u_k : B_k[x_1 := u_1, \dots, x_{k-1} := u_{k-1}]$$

The type of  $\text{coh}_{\Delta.A}(u_1, \dots, u_n)$  is  $A[x_1 := u_1, \dots, x_n := u_n]$ .



# Terms (example)

## Example (Identity)

If  $u : \star$  in context  $\Gamma$ , then

$$\text{coh}_{(x:\star).(x \simeq_{\star} x)}(u) : u \simeq_{\star} u$$

# $\infty$ -groupoids

## Definition

An  **$\infty$ -groupoid** is a globular set  $G$  equipped with, for every contractible context  $\Delta$  and every type  $A$  in  $\Delta$ , an operation

$$\mathbf{coh}_{\Delta.A} : (\eta \in \llbracket \Delta \rrbracket) \rightarrow \text{Ob}(\llbracket A \rrbracket_\eta)$$

where

$$\llbracket \star \rrbracket_\eta := G$$

$$\llbracket u \simeq_A v \rrbracket_\eta := \text{Hom}_{\llbracket A \rrbracket_\eta}(\llbracket u \rrbracket_\eta, \llbracket v \rrbracket_\eta)$$

$$\llbracket x \rrbracket_\eta := \eta(x)$$

$$\llbracket \mathbf{coh}_{\Delta.A}(u_1, \dots, u_n) \rrbracket_\eta := \mathbf{coh}_{\Delta.A}(\llbracket u_1 \rrbracket_\eta, \dots, \llbracket u_n \rrbracket_\eta)$$

$$\llbracket (x_1 : B_1, \dots, x_n : B_n) \rrbracket := \{(a_1, \dots, a_n) \mid a_k \in \text{Ob}(\llbracket B_k \rrbracket_{(a_1, \dots, a_{k-1})})\}$$

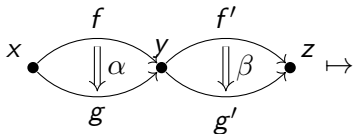
## Examples of operations

## Example

Every operation of bigroupoids corresponds to some  $\mathbf{coh}_{\Delta, A}$ .



$$g \circ f : x \simeq_{\star} z$$



$$\beta \star_0 \alpha : (f' \circ f) \simeq_{(x \simeq_{\star} z)} (g' \circ g)$$

More generally, everything with a contractible **input** and a well-formed **output**.

# Examples of $\infty$ -groupoids

## Examples

- Groupoids
- The fundamental  $\infty$ -groupoid of a topological space

# $\infty$ -groupoid of morphisms

## Proposition

*Let  $G$  be an  $\infty$ -groupoid and  $a, b : G$ .*

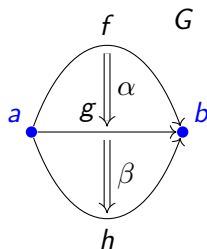
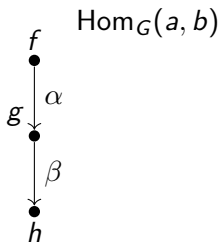
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Then  $\text{Hom}_G(a, b)$  has a natural structure of  $\infty$ -groupoid.



$$\mathbf{coh}_{\Delta.A}^{\text{Hom}_G(a,b)}(u_1, \dots, u_n) := \mathbf{coh}_{\Sigma\Delta.\Sigma A}^G(a, b, u_1, \dots, u_n)$$

## Summary

We defined *syntactically* the notions of

- contractible **input**
- well-formed **output** according to a given input
- coherence operation

This gives an elementary definition of **globular weak  $\infty$ -groupoid** which is

- easy to define and understand
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Thank you for your attention