# Universes in the category of cubical sets

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## Introduction

The goal of this note is to give a definition of two universes [1]  $p : \tilde{U} \to U$  and  $p_F : \tilde{U}_F \to U_F$  in the category of cubical set. This first universe is a universe of cubical sets. The second universe is the universe of "fibrant" cubical sets, and provides a model of type theory with dependent product, sum, identity types and function extensionality. Furthermore, it is fibrant and univalent.

## Cubical sets

#### Definition of the base category

A de Morgan algebra is a bounded distributive lattice A, with a top element 1 and a bottom element 0 and with an operation 1 - i satisfying

 $1 - 0 = 1 \quad 1 - 1 = 0 \quad 1 - (i \lor j) = (1 - i) \land (1 - j) \quad 1 - (i \land j) = (1 - i) \lor (1 - j)$ 

This notion differs from the one of Boolean algebra by requiring neither  $1 = i \lor (1-i)$  nor  $0 = i \land (1-i)$ . A prime example of a de Morgan algebra, which is not a Boolean algebra, is the interval [0, 1] with  $\max(i, j), \min(i, j)$  operations.

We assume a given (discrete) set of symbols/names/directions, not containing 0, 1. We let  $I, J, K, \ldots$ denote finite sets of such symbols. We also assume a function  $\mathsf{fresh}(I)$  which selects a name not in I. Let  $\mathcal{C}$  be the following precategory. The objects are finite sets of names  $I, J, K, \ldots$ . A morphism  $I \to J$ is a map  $I \to \mathsf{dM}(J)$ , where  $\mathsf{dM}(J)$  is the free de Morgan algebra on J. We think of f as a substitution and may write if the element f(i) in  $\mathsf{dM}(J)$ . If  $f: I \to J$  and  $g: J \to K$  we write  $fg: I \to K$  the composition of f and g. We write  $1_I: I \to I$  the identity map. A *cubical set* is a presheaf on  $\mathcal{C}^{opp}$ , i.e. a functor  $\mathcal{C} \to \mathsf{Set}$ .

Another equivalent definition of  $\mathcal{C}^{opp}(I,J)$  is the set of monotone maps  $2^I \times 2^I \to 2^J \times 2^J$ .

We shall need a few notions and properties of the base category that are listed in Appendix I.

A cubical set X is thus given by a family of sets X(I) together with a restriction map

$$X(I) \to X(J)$$

$$u \longmapsto uf$$

such that  $u1_I = u$  and (uf)g = u(fg). (We write uf for what is usually written X(f)(u), since we want to think about this operation as a substitution; the elements of X(I) for  $I = i_1, \ldots, i_n$  are thought of as elements  $u = u(i_1, \ldots, i_n)$  depending on  $i_1, \ldots, i_n$  and the restriction uf as a substitution operation.)

If X is a presheaf on the slice category  $\mathcal{C}/I$  we let  $\Gamma(X)$  be the set  $X(I, 1_I)$ . If X and Y are two presheaves on  $\mathcal{C}/I$  an element of  $\Gamma(X \to Y)$  is given by a family of maps  $w_{(J,f)} : X(J,f) \to Y(J,f)$  such that  $(w_{(J,f)} \ u)g = w_{(K,fg)} \ ug$ . We also can consider the presheaf P(X), with  $P(X)(J,f) = X(j,J,f\iota_j)$ where  $j = \mathsf{fresh}(J)$ . We can then define the set  $\mathsf{lso}(X,Y)$  as a subset of

$$\Gamma((X \to Y) \times (Y \to X) \times (X \to P(Y)) \times (Y \to P(X)))$$

## The universe of cubical sets

We fix a set V of small sets. Each element a in V determines a small set El(a). The pair V, El defines then a (pre)category by taking the set of morphisms between a and b to be  $El(a) \to El(b)$ . If  $\mathcal{D}$  is a (pre)category, we define the set of V-valued presheaves on  $\mathcal{D}$  to be the set of functors from  $\mathcal{D}^{opp}$  to this precategory.

Given I, we can consider the set of V-valued functors on the slice (pre)category C/I. Such a functor A is given by a family of sets A(J, f) in V and restriction maps  $El(A(J, f)) \to El(A(K, fg))$ . If A is such a functor, we can define a new functor P(A) by taking P(A)(I, f) to be  $A(i, I, f\iota_i)$  where i = fresh(I). If p is in P(A)(I, f) we can consider p0 = p(i0) and p1 = p(i1) in A(I, f). If a is in A(I, f) we consider the constant path  $\overline{a} = a\iota_i$  in P(A)(I, f).

We define U(I) to be the set of all V-valued presheaves on  $\mathcal{C}/I$ . The restriction map  $U(I) \to U(J)$ ,  $A \mapsto Af$  is defined by letting Af be the composition of A and the functor  $\mathcal{C}/J \to \mathcal{C}/I$ .

If A is an element of the set U(I) we write  $\Gamma(A)$  the set of "global element" of A, which is the set  $A(I, 1_I)$ . If  $f: I \to J$ , we have  $\Gamma(Af) = A(J, f)$  and restriction maps  $\Gamma(A) \to \Gamma(Af)$ ,  $u \mapsto uf$ .

We let  $\tilde{U}(I)$  be the set of pairs A, u where A is an element of U(I) and u an element of the set  $\Gamma(A)$ . We define (A, u)f = (Af, uf). We define the natural transformation  $p: \tilde{U} \to U$  by p(A, u) = A.

**Proposition 0.1**  $p: \tilde{U} \to U$  defines a universe [1] in the category of cubical sets.

Indeed if X is a cubical set and  $\sigma : X \to U$  then we can define the cubical set  $(X, \sigma)$  by taking  $(X, \sigma)(I)$  to be the set of pairs x, u with x in X(I) and u in  $\Gamma(\sigma x)$ .

## Glueing operation on cubical sets

We assume to have an operation  $\mathsf{glue}_I A \vec{\sigma}$  in U(I), for A in U(I) and a system of maps  $\sigma_{\alpha}$  in  $T_{\alpha} \to A\alpha$ , which satisfies

- 1. glue  $A \vec{\sigma} = T$  if  $\vec{\sigma}$  is ()  $\mapsto \sigma$  with  $\sigma : T \to A$
- 2. regularity:  $\mathsf{glue}_I A (\vec{\sigma}, \alpha \mapsto id_{A\alpha}) = \mathsf{glue}_I A \vec{\sigma}$
- 3. uniformity:  $(\mathsf{glue}_I \ A \ \vec{\sigma})f = \mathsf{glue}_I \ Af \ \vec{\sigma}f \ \text{if} \ f: I \to J$

A system of maps  $\vec{\sigma}$  is given by a sieve L in S(I) (as defined in Appendix I) and a compatible family of maps  $\sigma_{(J,f)}$  in  $T_{(J,f)} \to Af$  indexed by (J, f) in L. If we have two systems on L and M respectively which coincide on  $L \cap M$  then they define a system over the union L, M. For the regularity condition, it is assumed that the system defined by  $\alpha \mapsto id_{A\alpha}$  and the system  $\vec{\sigma}$  are compatible, that is we have  $\sigma_{(J,f)}u = u$  if  $f \leq \alpha$ .

Furthermore any element of  $\Gamma(\mathsf{glue}_I \ A \ \vec{\sigma})$  is uniquely determined by a tuple  $u, \vec{t}$  with u in  $\Gamma(A)$  and  $t_{\alpha}$  in  $\Gamma(T_{\alpha})$ , such that  $u\alpha = \sigma_{\alpha}t_{\alpha}$ . If we write  $(u, \vec{t})$  this element, we have  $(u, \vec{t})f = (uf, \vec{t}f)$ . We also have a map  $\delta_I$ :  $\mathsf{glue}_I \ A \ \vec{\sigma} \to A$  such that  $\delta_I(u, \vec{t}) = u$ .

If we don't require the regularity condition, then we can define  $\Gamma(\mathsf{glue}_I \ A \ \vec{\sigma})$  to be the set of all such tuple  $u, \vec{t}$ . (This is actually enough for showing that the universe  $U_F$  defined later is univalent; the regularity condition is needed to show that this universe is fibrant.) One possible definition of such a glueing operation satisfying the regularity condition is in Appendix II.

## Dependent sets

If X is a cubical set, the *category of element of* X has for object pair  $(I, \rho)$  with  $\rho$  in X(I) and a morphism between  $I, \rho$  and  $J, \nu$  is a map  $f: I \to J$  such that  $\nu = \rho f$ . If X is a cubical set, a *fibration*  $X \vdash B$  over X is given by a V-valued presheaf on the category of element of X.

Such a fibration defines a cubical set X.B by taking (X.B)(I) to be the set of pairs  $(\rho, v)$  with  $\rho$  in X(I) and v in  $B(I, \rho)$ .

## The universe of fibrant cubical sets

If A is an element of the set U(I) we define the set of composition operations and the set of transport operations for A.

#### Composition

A composition operation for A is given by a family of operations  $\operatorname{comp}_f u \vec{p}$  element in El(A(I, f)), u in the set El(A(I, f)) and  $\vec{p}$  a system for P(A) such that  $u\alpha = p_{\alpha}0$ . We should have

- 1.  $\operatorname{comp}_f u [() \mapsto p] = p1$
- 2. regularity:  $\operatorname{comp}_{f} u \ (\vec{p}, \alpha \mapsto \overline{u\alpha}) = \operatorname{comp}_{f} u \ \vec{p}$
- 3. uniformity:  $(\operatorname{comp}_f u \ \vec{p})g = \operatorname{comp}_{fg}^j ug \ \vec{pg}$  if  $g: J \to K$ .

#### Transport

A transport operation for A is given by a family of operations  $transp_{f}^{i}$  in

$$El(A(J-i, f(i0))) \rightarrow El(A(J-i, f(i1)))$$

for  $f: I \to J$  and i in J. Furthermore we should have

- 1. regularity: transp<sup>i</sup><sub>f</sub>  $u_0 = u_0$  if we have  $f = f(i0)\iota_i$
- 2. uniformity:  $(\operatorname{transp}_{f}^{i} u_{0})g = \operatorname{transp}_{f(g,i=j)}^{j} u_{0}g$  if  $g: J i \to K$  and j not in K

We let  $U_F(I)$  be the set of element in U(I) together with a composition and transport operation. If  $(\mathsf{comp}_h, \mathsf{transp}_h^i)$  is a composition and transport for A, V-valued presheaf on  $\mathcal{C}/I$ , then  $(\mathsf{comp}_{fg}^j, \mathsf{comp}_{fg}^j)$  is a composition and transport for Af, V-valued presheaf on  $\mathcal{C}/J$ .

We define in this way a restriction map  $U_F(I) \to U_F(J)$  and a cubical set  $U_F$ .

There is a projection map  $U_F \to U$  but  $U_F$  is not a subpresent of U.

A particular case of regularity can be seen as a kind of  $\alpha$ -conversion for transport

$$\mathsf{transp}_{f}^{i}u_{0} = \mathsf{transp}_{f(1_{K},i=j)}^{j}u_{0}$$

if  $f: I \to K, i$  and j is not in K.

#### Kan cubical sets

Notice that an element of U() is given by a V-valued presheaf on  $\mathcal{C}$  and each transport function

$$\mathsf{transp}^i:A_{I-i}\to A_{I-i}$$

is constant by regularity.

A Kan cubical set is a cubical set X together with a composition operation  $\operatorname{comp}_I u \vec{p}$  in X(I) with u in X(I) and  $\vec{p}$  a system for X such that

- 1.  $\operatorname{comp}_{I} u [() \mapsto p] = p1$
- 2. regularity:  $\operatorname{comp}_{I} u (\vec{p}, \alpha \mapsto \overline{u\alpha}) = \operatorname{comp}_{I} u \vec{p}$
- 3. uniformity:  $(\operatorname{comp}_{I} u \ \vec{p})f = \operatorname{comp}_{J}^{j} uf \ \vec{p}f$

#### Kan fibration

If X is a cubical set, the category of element of X has for object pair  $(I, \rho)$  with  $\rho$  in A(I) and a morphism between  $I, \rho$  and  $J, \nu$  is a map  $f: I \to J$  such that  $\nu = \rho f$ . If X is a cubical set, a Kan fibration  $X \vdash B$ over X is given by a V-valued presheaf on the category of element of X which admits composition and transport operations. We should have

- 1.  $\operatorname{comp}_{I,\rho} u \ [() \mapsto p] = p1$
- 2. regularity: comp<sub>I,\rho</sub> u  $(\vec{p}, \alpha \mapsto \overline{u\alpha}) = \text{comp}_{I,\rho} u \vec{p}$
- 3. uniformity:  $(\operatorname{comp}_{I,\rho} u \ \vec{p})f = \operatorname{comp}_{J,\rho f}^{j} uf \ \vec{p}f$  if  $g: I \to J$  and j is not in J

for the composition operation, and

- 1. regularity: transp<sup>i</sup><sub>I</sub>  $u_0 = u_0$  if we have  $\rho = \rho(i0)\iota_i$
- 2. uniformity:  $(\operatorname{transp}_{I,\rho}^{i} u_{0})g = \operatorname{transp}_{(J,j),\rho(g,i=j)}^{j} u_{0}g$  if  $g: I i \to J$  and j not in J

for the transport operation.

Whenever  $X \vdash B$  we can define the associated total space X.B by taking (X.B)(I) to be the set of pairs  $\rho, u$  with  $\rho$  in A(I) and u in  $B(I, \rho)$  and  $(\rho, u)f = \rho f, uf$ . We have a projection  $p : X.B \to X$  defined by  $p(\rho, u) = \rho$ .

## **Definition of** $\tilde{U}_F \to U_F$

By change of base of  $p: \tilde{U} \to U$  along the projection  $U_F \to U$  we get a map  $\tilde{U}_F \to U_F$ . Concretely, an element of  $\tilde{U}_F(I)$  is given by an element A in U(I), a composition and a transport operation on A, and an element of  $\Gamma(A)$ .

We define  $\operatorname{comp}_{I,A} u \ \vec{u}$  to be  $\operatorname{comp}_{1_I} u \ \vec{u}$  and  $\operatorname{transp}_{I,A}^i$  to be  $\operatorname{transp}_{1_I}^i$ .

**Proposition 0.2** With these operations of composition and transport,  $U \vdash B$  is a Kan fibration.

Given A and B in  $U_F(I)$  we can define  $\mathsf{Id}(I, A, B)$  to be the set of elements E in  $U_F(I, i)$  satisfying E(i0) = A and E(i1) = B, where  $i = \mathsf{fresh}(I)$ . We also have defined already the set  $\mathsf{Iso}(I, A, B)$ . This corresponds to two fibrations  $U_F \times U_F \vdash \mathsf{Id}$  and  $U_F \times U_F \vdash \mathsf{Iso}$ .

**Theorem 0.3** We have a natural transformation  $lso(I, A, B) \rightarrow ld(I, A, B)$ .

**Theorem 0.4**  $U_F$  has a structure of a Kan cubical set.

All operations are defined in term of the glueing operation on cubical sets.

## Appendix I: Properties of the base precategory

We say that a map  $f: I \to J$  is *strict* if *if* is neither 0 nor 1 for all *i* in *I*. One key remark is the following.

**Lemma 0.5** If  $f: I \to J$  is strict and  $\psi$  in dM(I) such that  $\psi f = b$  (where b is 0 or 1) then already  $\psi = b$ .

(This does not hold if we work with Boolean algebra instead of de Morgan algebra. For instance the map  $(i = j) : \{i, j\} \to \{j\}$  is strict and  $(i \land (1 - j))(i = j) = 0$  in a Boolean algebra, but  $i \land (1 - j)$  is neither 0 nor 1.)

A face map  $\alpha: I \to I_{\alpha}$  is a map such that  $i\alpha$  is either 0, 1 or *i* for all *i* in *I*. We write  $I_{\alpha}$  the subset of element *i* such that  $i\alpha = i$ , and  $dom(\alpha) = I - I_{\alpha}$  is the *domain* of  $\alpha$ . If  $\iota_{\alpha}: I_{\alpha} \to I$  is the inclusion, we have  $\iota_{\alpha}\alpha = 1$  and hence any face map  $\alpha$  is *epi*. If  $f: I \to J$  we write  $f \leq \alpha$  to mean that there exists a map f' (uniquely determined) such that  $f = \alpha f'$ . This means that  $if = i\alpha$  for all i in the domain of  $\alpha$ . This defines a poset structure on the set of face maps  $\alpha : I \to I_{\alpha}$  and this poset is a partial meet-semilattice: if  $\alpha$  and  $\beta$  are compatible then they have a meet  $\gamma = \alpha \land \beta$  with  $I_{\gamma} = I_{\alpha} \cap I_{\beta}$ .

**Corollary 0.6** If  $fg \leq \alpha$  and g is strict then  $f \leq \alpha$ .

*Proof.* For any *i* in the domain of  $\alpha$  we have  $i\alpha = ifg$  and so  $i\alpha = if$  since  $i\alpha = 0$  or 1 and by Lemma 0.5.

Any map  $f: I \to J$  can be written uniquely as the composition  $f = \alpha h$  of a face map  $\alpha: I \to I_{\alpha}$ and a map  $h: I_{\alpha} \to J$  which is strict.

If i not in I we write  $\iota_i : I \to I, i$  the inclusion. If i is in I we write  $(i0) : I \to I - i$  and  $(i1) : I \to I - i$  the two face operation for i.

**Lemma 0.7** If we have  $\alpha f = \beta g$  with  $f: I_{\alpha} \to J$  and  $g: I_{\beta} \to J$  then  $\alpha$  and  $\beta$  are compatible. If  $\gamma$  is the meet of  $\alpha$  and  $\beta$ , then there exists a unique  $h: I_{\gamma} \to J$  such that  $\alpha f = \gamma h = \beta g$ . If we write  $\alpha \alpha_1 = \gamma = \beta \beta_1$  then  $\alpha_1 f = h = \beta_1 g$ .

#### Systems

We define S(I) to be the set of sieves L over I such that f is in L whenever fg is in L and g is strict. Such a sieve L is completely characterised by its subset of face maps  $\alpha : I \to I_{\alpha}$ . This defines a cubical set S.

If A is a presheaf on the slice category  $C^{opp}/I$  and L in S(I) a L-system for A is given by a family  $a_{(J,f)}$  in Af for (J, f) in L such that  $a_{(J,f)}g = a_{(K,fg)}$  for all  $g: J \to K$ .

If  $f: I \to J$  and we have a L-system  $\vec{a}$  we define a Lf system  $\vec{b} = \vec{a}f$  by taking  $b_{(K,g)} = a_{(K,fg)}$ .

A L-system for A is completely determined by the family  $[\alpha \mapsto a_{\alpha}]$  for  $\alpha$  face in L. If L is the union of M and N, and we have a M-system  $\vec{a}$  and a N-system  $\vec{b}$  that coincide on  $M \cap N$  then they define a system  $\vec{a}, \vec{b}$  on the union M, N.

## Appendix II: Definition of the glueing operation

An *I*-element in V is a tuple  $(u_{\alpha})$  indexed by the face operations of I. An *I*-set is a set all element of which are *I*-elements. If X is an *I*-set, and u is an element of X we can consider the element  $u_{\alpha}$  for each face operation  $\alpha$  on I.

We refine the definition of U(I) by imposing A(J, f) to be a *J*-set and the restriction operation  $A(J, f) \to A(J\beta, f\beta), u \mapsto u\beta$  to satisfy  $u\beta_{\gamma} = u_{\beta\gamma}$  for each face operation  $\gamma$  on  $J\beta$ .

With this refinement, we can define, given u in  $\Gamma(A)$  and  $t_{\alpha}$  in  $\Gamma(T_{\alpha})$  such that  $\sigma_{\alpha}t_{\alpha} = u\alpha$ , a tuple  $(u, \vec{t})$  by  $(u, \vec{t})_{\beta} = t_{\beta}$  if  $\beta \leq L$  and  $(u, \vec{t})_{\beta} = u_{\beta}$  otherwise. Notice that we have  $(u, \vec{t}) = u$  if all  $\sigma_{\alpha}$  are identity maps. We then define  $\Gamma(\mathsf{glue}_I A \vec{\sigma})$  to be the *I*-set of elements  $(u, \vec{t})$ .

If v is in  $\Gamma(\mathsf{glue}_I \ A \ \vec{\sigma})$  we define  $(\delta_I v)_\beta = \sigma_\beta v_\beta$  if  $\beta \leq L$  and  $(\delta_I v)_\beta = v_\beta$  otherwise.

### References

[1] V. Voevodsky. Notes on type systems. github.com/vladimirias/old\_notes\_on\_type\_systems, 2009-2012.