Stable ∞ -Categories (Lecture 3)

February 2, 2011

In the last lecture, we introduced the definition of an ∞ -category as a generalization of the usual notion of category. This definition is one way of formalizing the notion of a higher category in which all k-morphisms are invertible for k > 1. Many other approaches are possible. The following is probably more intuitive:

Definition 1. A topological category is a category \mathcal{C} together with a topology on the set $\operatorname{Hom}_{\mathcal{C}}(X,Y)$ for every pair of objects X and Y, such that the composition maps $\operatorname{Hom}_{\mathcal{C}}(X,Y) \times \operatorname{Hom}_{\mathcal{C}}(Y,Z) \to \operatorname{Hom}_{\mathcal{C}}(X,Z)$ are continuous. (In other words, a category which is *enriched* over the category of topological spaces.) If \mathcal{C} is a topological category containing a pair of objects X and Y, we will denote $\operatorname{Hom}_{\mathcal{C}}(X,Y)$ by $\operatorname{Map}_{\mathcal{C}}(X,Y)$ when we wish to emphasize that we are thinking of it as a topological space.

Remark 2. To accommodate certain examples, it is convenient to modify Definition 1 by working with *compactly generated* topological spaces rather than topological spaces. That is, we require that each $\operatorname{Map}_{\mathfrak{C}}(X,Y)$ be compactly generated, and require that composition is given by continuous maps

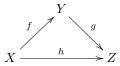
$$\operatorname{Map}_{\mathfrak{C}}(X,Y) \times \operatorname{Map}_{\mathfrak{C}}(Y,Z) \to \operatorname{Map}_{\mathfrak{C}}(X,Z)$$

where the product is taken in the category of compactly generated topological spaces. This is a technical point which may be safely ignored.

The theory of ∞ -categories is closely related to the theory of topological categories.

Construction 3 (Sketch). Let \mathcal{C} be a topological category. We define a simplicial set $N^t(\mathcal{C})$, the homotopy coherent nerve of \mathcal{C} , as follows:

- The 0-simplices of $N^t(\mathcal{C})$ are the objects of \mathcal{C} .
- The 1-simplices of $N^t(\mathcal{C})$ are morphisms $f: X \to Y$ in \mathcal{C} .
- The 2-simplices of $N^t(\mathcal{C})$ are given by (noncommuting) diagrams



in C, together with a choice of path from h to $g \circ f$ in Map_C(X, Z).

• ...

Example 4. Let \mathcal{C} be an ordinary category. We can regard \mathcal{C} as a topological category by endowing each mapping set $\operatorname{Hom}_{\mathcal{C}}(X,Y)$ with the discrete topology.

It turns out that for any topological category \mathbb{C} , the homotopy coherent nerve $\mathrm{N}^t(\mathbb{C})$ is an ∞ -category. Moreover, there is a sort of converse: every ∞ -category is equivalent to $\mathrm{N}^t(\mathbb{C})$ for some topological category \mathbb{C} , and the topological category \mathbb{C} is essentially unique (up to a suitable notion of weak homotopy equivalence). In other words, the construction $\mathbb{C} \mapsto \mathrm{N}^t(\mathbb{C})$ determines an equivalence between the theory of topological categories and the theory of ∞ -categories. From this point forward, we will work at an informal level and freely mix these two notions. For example, if S is an ∞ -category containing a pair of 0-simplices x and y, we will use $\mathrm{Map}_S(x,y)$ to denote a mapping space between x and y, when viewed as objects of a topological category whose homotopy coherent nerve is equivalent to S.

Remark 5. To any topological category \mathcal{C} (and therefore to any ∞ -category) we can associate an ordinary category $h\mathcal{C}$, called the *homotopy category* of \mathcal{C} . It has the same objects, with morphisms given by $\operatorname{Hom}_{h\mathcal{C}}(X,Y) = \pi_0 \operatorname{Map}_{\mathcal{C}}(X,Y)$.

Example 6. The collection of finite CW complexes forms a topological category: for any pair of finite CW complexes X and Y, we can endow the set of continuous maps $\operatorname{Hom}(X,Y)$ with the compact-open topology. If we use the convention of Remark 2, then this generalizes to arbitrary CW complexes. We will denote the homotopy coherent nerve of this (larger) topological category by S, and refer to it as the ∞ -category of spaces.

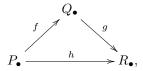
Here is an example of greater interest to us:

Example 7 (Sketch). Let A be an associative ring. There is an ∞ -category $\mathcal{D}^{perf}(A)$ which may be described as follows:

• The 0-simplices of $\mathcal{D}^{perf}(A)$ are given by bounded chain complexes of finitely generated projective left A-modules

$$\cdots \rightarrow P_2 \rightarrow P_1 \rightarrow P_0 \rightarrow P_{-1} \rightarrow \cdots$$

- A 1-simplex of $\mathcal{D}^{\mathrm{perf}}(A)$ consists of a pair of chain complexes P_{\bullet} and Q_{\bullet} , together with a map of chain complexes $f: P_{\bullet} \to Q_{\bullet}$.
- A 2-simplex of $\mathcal{D}^{perf}(A)$ consists of a (not necessarily commutative) diagram of chain complexes



together with a chain homotopy from h to $g \circ f$.

• Higher dimensional simplices are defined using higher-order chain homotopies.

The homotopy category of $\mathcal{D}^{perf}(A)$ is equivalent to the category **hPerf** of the previous lecture.

Our next goal is to axiomatize some of the special features enjoyed by ∞ -categories of the form $\mathcal{D}^{\mathrm{perf}}(A)$. First, we need to introduce a bit of terminology. Let \mathcal{C} be an ∞ -category and \mathcal{I} an ordinary category. It makes sense to speak of *functors* from \mathcal{I} to \mathcal{C} : these are given by maps of simplicial sets $N(\mathcal{I}) \to \mathcal{C}$. We can use this notion to make sense of commutative diagrams in \mathcal{C} . For example, a square diagram

$$\begin{array}{ccc} X \longrightarrow Y \\ \downarrow & \downarrow \\ X' \longrightarrow Y' \end{array}$$

in \mathcal{C} is just a map of simplicial sets $\Delta^1 \times \Delta^1 \to \mathcal{C}$.

Definition 8. Let \mathcal{C} be an ∞ -category. We will say that an object $0 \in \mathcal{C}$ is a zero object if, for every object $X \in \mathcal{C}$, the mapping spaces

$$\operatorname{Map}_{\mathfrak{C}}(0,X)$$
 $\operatorname{Map}_{\mathfrak{C}}(X,0)$

are contractible. We will say that C is *pointed* if it admits a zero object.

If \mathcal{C} is a pointed ∞ -category, then for any pair of objects X and Y there is a zero map from X to Y, given by the composition

$$X \to 0 \to Y$$

where 0 is a zero object of C. This map is well-defined up to a contractible space of choices.

Definition 9. Let \mathcal{C} be a pointed ∞ -category. A *triangle* in \mathcal{C} consists of a diagram

$$X \xrightarrow{f} Y \xrightarrow{g} Z$$

in \mathcal{C} , together with a path from $g \circ f$ to the zero map in $\operatorname{Map}_{\mathcal{C}}(X, Z)$ (in other words, a *nullhomotopy* of $g \circ f$). More formally: a triangle in \mathcal{C} is a square diagram

$$\begin{array}{ccc}
X & \xrightarrow{f} & Y \\
\downarrow & & \downarrow g \\
0 & \longrightarrow & Z
\end{array}$$

where 0 is a zero object of \mathcal{C} .

Suppose we are given a triangle

$$X \xrightarrow{f} Y \xrightarrow{g} Z$$

in a pointed ∞ -category \mathbb{C} . We will say that this triangle is a *fiber sequence* if, for every object $C \in \mathbb{C}$, the associated sequence of topological spaces

$$\operatorname{Map}_{\mathcal{C}}(C,X) \to \operatorname{Map}_{\mathcal{C}}(C,Y) \to \operatorname{Map}_{\mathcal{C}}(C,Z)$$

is a homotopy fiber sequence. In this case, X is determined (up to equivalence) by g. We will say that X is the fiber of g and write X = fib(g).

Dually, we say that

$$X \xrightarrow{f} Y \xrightarrow{g} Z$$

is a cofiber sequence if, for every object $C \in \mathcal{C}$, the associated sequence of topological spaces

$$\operatorname{Map}_{\mathfrak{C}}(Z,C) \to \operatorname{Map}_{\mathfrak{C}}(Y,C) \to \operatorname{Map}_{\mathfrak{C}}(X,C)$$

is a homotopy fiber sequence. In this case, Z is determined (up to equivalence) by f. We will say that Z is the *cofiber of* g and write Z = cofib(g).

Definition 10. Let \mathcal{C} be an ∞ -category. We say that \mathcal{C} is *stable* if the following conditions are satisfied:

- (1) C is pointed: that is, there is a zero object of C.
- (2) Every morphism $f: X \to Y$ in \mathcal{C} has a fiber and a cofiber.
- (3) A triangle $X \xrightarrow{f} Y \xrightarrow{g} Z$ in \mathcal{C} is a fiber sequence if and only if it is a cofiber sequence.

Example 11. There is a stable ∞ -category Sp whose objects are spectra. The homotopy category hSp is the classical *stable homotopy category*.

Example 12. The ∞ -category $\mathcal{D}^{\text{perf}}(A)$ considered above is stable.

Let \mathcal{C} be a stable ∞ -category. We define an abelian group $K_0(\mathcal{C})$ as follows: $K_0(\mathcal{C})$ is obtained from the free abelian group generated by symbols [X], where X is an object of \mathcal{C} , subject to the following relation: if there is a fiber sequence

$$X \to Y \to Z$$
,

then [Y] = [X] + [Z].

Remark 13. Let \mathcal{C} be a stable ∞ -category. One can show that the homotopy category of \mathcal{C} is triangulated. Moreover, the K-group $K_0(\mathcal{C})$ depends only on the homotopy category of \mathcal{C} , viewed as a triangulated category. However, when discussing more sophisticated invariants of \mathcal{C} (like higher K-groups or L-groups) it is better not to pass to the homotopy category.

Example 14. If A is a ring, then the K-group $K_0(\mathbb{D}^{\operatorname{perf}}(A))$ is canonically isomorphic to the group $K_0(A)$ defined in the last lecture. In particular, if A is a field, then there is a canonical isomorphism $K_0(\mathbb{D}^{\operatorname{perf}}(A)) \simeq \mathbb{Z}$. If P_{\bullet} is an object of $\mathbb{D}^{\operatorname{perf}}(A)$, then $[P_{\bullet}] \in K_0(\mathbb{D}^{\operatorname{perf}}(A)) \simeq \mathbb{Z}$ can be identified with the Euler characteristic

$$\sum_{i} (-1)^{i} \dim_{A} H_{i}(P_{\bullet})$$

of the chain complex P_{\bullet} .

In general, if we are given an object X of a stable ∞ -category \mathcal{C} , then we can view the class $[X] \in K_0(\mathcal{C})$ as a kind of "generalized Euler characteristic" of X. It is in general not an integer, but an element of the abelian group $K_0(\mathcal{C})$ which depends on \mathcal{C} . We can think of the construction $\mathcal{C} \mapsto K_0(\mathcal{C})$ as a kind of categorificatied Euler characteristic:

Input	Invariant
vector space V	dimension $\dim(V) \in \mathbf{Z}$
complex of vector spaces	Euler characteristic $\chi \in \mathbf{Z}$
stable ∞ -category $\mathcal C$	abelian group $K_0(\mathcal{C})$
object of a stable ∞ -category $\mathcal C$	K -theory class $[X] \in K_0(\mathcal{C})$

However, these are not the invariants we really want to study in this class. Recall that if V is a finite dimensional vector space over \mathbb{R} with a nondegenerate quadratic form q, then V is determined (up to isometry) by two invariants: the dimension of V and the signature of V. It is the latter that we would really like to generalize. Let us briefly indicate the form that this generalization will take:

Input	Invariant
nondegenerate quadratic space (V,q) over $\mathbb R$	signature $\sigma(V,q) \in \mathbf{Z}$
Poincare chain complex (V_*,q) over $\mathbb R$	signature σ of middle homology
stable ∞ -category $\mathcal C$ with quadratic functor Q	L -group $L_0(\mathcal{C}, Q)$
Object $X \in \mathcal{C}$ satisfying Poincare duality	$[X] \in L_0(\mathcal{C}, Q)$

We will start making sense of some of these words in the next lecture.