

ON THE SECURITY OF MULTI-PARTY PROTOCOLS IN DISTRIBUTED SYSTEMS

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ABSTRACT

Security of protocols for network communication has received considerable attention in recent years. We concentrate on ensuring the security of cryptographic protocols in distributed systems.

In a distributed system, beyond eavesdropping, a saboteur may impersonate another user or alter messages being sent. A saboteur who is also a user may send conflicting messages or use other illegal messages in order to uncover secret information.

The problem we address, in its most general form, is: "given a multi-party protocol which is provably secure when all the participants monitor every message being sent, can the protocol be modified to be secure in a distributed system?"

We use the Byzantine Agreement, Crusader Agreement, and other specific checks to improve protocols by making them secure in a general distributed network. We examine the trade-off between detection of faulty behaviour and the number of messages exchanged.

1. Introduction

The main purpose of a cryptosystem is to protect private information. Cryptographic protocols enable users to employ the cryptosystem while com-

[†] Part of this work has been done while the first author visited IBM Research Center, San Jose, California.

municating with each other. A cryptosystem is secure if it cannot be "broken" using various mathematical tools. The security of a cryptographic protocol is measured by its ability to prevent eavesdroppers and other non-participants from understanding the information being exchanged. Distributed cryptographic protocols are intended to guarantee the security of private information in case one cannot trust even the users participating in the protocol itself. We will make sure that private information will not be disclosed even in the case that several participants collaborate in attempting to cause such disclosure.

The security of cryptographic protocols has been discussed in previous papers (DEK, DLM, DY, LW, NS). In this paper we assume that we are given a protocol which is secure in a *round-table environment* (or round-table secure). That is, the protocol is secure provided every user is able to see every message being exchanged between every pair of users in the system, provided users are consistently following the protocol, and provided deviations from the protocol can be detected. We will show how to modify such a protocol to make it secure in a distributed system in which a user can see only information he himself receives. For example, all the protocols presented in (LW) are round-table secure. But the same protocols, when used in a distributed system are no longer secure.

The difference between a round-table and a distributed system is that in the latter a user can slightly deviate from the protocol in a way that the recipient of the message cannot be aware of, and by doing so he is able to uncover secret information. As a matter of fact, a saboteur in a distributed system can do whatever he wants as long as the user receiving the message does not suspect a misbehaviour, or even if he suspects, he is unable to obtain a "proof of misbehaviour".

The methods we will give for improving round-table secure protocols by making them distributed-secure produces protocols that are fault-tolerant in a very broad sense. The protocols will be able to sustain **any** malicious behaviour without ever revealing an individual's secret. We make no assumptions about the type of faulty behaviour nor about the communication network. We guarantee that in the case that the participants are all faithful, the protocol proceeds as usual. A malfunction may cause the protocol to stop. However, even in this case a saboteur cannot uncover private information. The algorithms we use will try to overcome the faulty behaviour, but we cannot guarantee to identify all the faulty users, as one might have hoped. The reason is that a faulty user can behave in a way that does not disclose his faultiness. However in cases where faultiness may endanger the security of the protocol, a faulty user will be detected.

2. The Model

Let U be a set of users participating in a given network. For simplicity we assume that all the users in U participate in the protocol. Moreover, we assume that the network is such that every two users can communicate directly. To relax this assumption one can follow the results of (Da, LSP) and obtain similar restrictions on the network connectivity. Let CU be the subset of correct (or

faithful) users, and TU (or saboteurs). We assume that the members of which set are the protocols and correctly exchange the behaviour of saboteurs in the protocol. Notice that saboteurs can, however, the can behave in a way that saboteurs cannot break.

Let t be an upper bound on the number of times a user can deviate in the protocol, that is, the protocol is parametrized by t .

We assume that a user can detect a message can be detected if one needs an upper bound on the number of times a message he receives.

In the analysis of the protocol we consider the behaviour of the protocol by eavesdroppers. The behaviour in the protocol of a faulty user could have been covered by this extension.

Let MSG be the set of messages. The operation of forming a message is denoted by f .

A *synchronized* sequence of phases (k, u) where nodes correspond to MSG according to $T_k(u, v) = f(k, I_u, M(k, u, v))$ where I_u is the user u , and $M(k, u, v)$ is the message received from messages he receives.

The phases are numbered k , a user should send a message in his inedges.

A protocol works if $M(k, u) = M(k-1, u)$ has the same information.

A protocol is *round-table secure* if a faithful user sends a message to users a, b we have $M(k, a) = M(k, b)$.

A protocol works if a faithful user u , $M(k, u)$ is the message obtained only by a faithful user.

We assume the following properties:

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For simplicity we reover, we assume icate directly. To and obtain similar set of correct (or

faithful) users, and TU be the rest of the users, named the traitors (faulty users or saboteurs). We assume that faithful users do not know which users are members of which sets. Faithful users behave correctly; they follow the protocols and correctly execute the algorithms. There are no assumptions on the behaviour of saboteurs; they may even collaborate in trying to break the protocol. Notice that saboteurs may know who are the members of each set. Moreover, they can behave faithfully, or at least pretend to do so. We do assume that saboteurs cannot break the cryptosystem.

Let t be an upper bound on the number of saboteurs that may participate in the protocol, that is, t is the cardinality of the set TU . Our results are parametrized by t .

We assume that users communicate synchronously and thus an absence of a message can be detected. The synchronous behaviour can be relaxed, but then one needs an upper bound for the time it takes for a faithful user to respond to a message he receives (FLP).

In the analysis that follows, we assume that no message has been stopped by eavesdroppers. To overcome the stopping we need to include this misbehaviour in the parameter t in some way (if this possibility was not limited, one faulty user could have isolated every other user from all others). We will not cover this extension here.

Let MSG be the set of possible messages. We assume MSG is closed under the operation of forming sequences from MSG .

A *synchronized multi-party protocol* P for a set of users U is a finite sequence of phases G_1, G_2, \dots, G_l . Each phase is a directed graph $G_k(U, E_k, T_k)$ where nodes correspond to the users in U , and the edges E_k are labeled from MSG according to T_k . For every directed edge (u, v) in E_k , $T_k(u, v) = f(k, I_u, M(k, u))$, where f is a function of I_u , the private information of user u , and $M(k, u)$, that contains the information u obtains through phase k from messages he receives. ($M(1, u)$ is empty for every faithful user u).

The phases are numbered with consecutive positive integers. At each phase k , a user should send the messages on his outedges and receive the messages on his inedges.

A protocol works in a *round-table* environment if for every faithful user u , $M(k, u) = M(k-1, u) \cup \{T_k(a, b) \mid a, b \in U\}$. In other words, every faithful user has the same information about every message that was sent in each phase.

A protocol is *round-table secure* if it is secure under the condition that a faithful user sends a message at the k th phase only if for every pair of faithful users a, b we have $M(k-1, a) = M(k-1, b)$.

A protocol works in a distributed system if at every phase k and for every faithful user u , $M(k, u) = M(k-1, u) \cup \{T_k(a, u) \mid a \in U\}$. In other words, a faithful user obtains only the messages he received at each phase.

We assume the existence of a cryptographic signature scheme with the following properties:

- (1) Every user x has a distinct signature function S_x with which he signs messages.
- (2) Every user can identify the signature of every other user and can extract the message from the signed message.
- (3) No user (not even a saboteur) can forge the signature of another user.
- (4) Every change in a signed message which is not done by the user who signed it can be detected by any other user.
- (5) The signature functions do not commute, i.e. for every message M $S_x S_y(M) \neq S_y S_x(M)$ whenever $x \neq y$.

A signature scheme with the above properties can be constructed using a (secure) public-key cryptosystem (DH, RSA). We further assume that the cryptographic system used for signatures is independent of the one used for encryption.

using the cryptographic signature scheme one can obtain messages with several signatures, can extract the contents of a message, and can identify the various signatures (and their order) a message carries. This will be the way we will use the signature scheme in the coming sections.

We use the following notation: A user notarizes a message if he signs it and sends it to all users. (Our algorithm works also if faulty users are able to remove signatures notarizing a message in an undetectable way). For simplicity we will assume that when a faithful user sends a message he also sends it to himself. A message is said to be k -dense if its contents is followed (notarized) by exactly k distinct signatures. Notice that the contents of a message can be another message which by itself carries signatures. We assume that the content of a message is uniquely defined. (In fact, it follows from our definition of a protocol).

3. Distributed Agreements

The security of a round-table secure protocols is based on the fact that all the faithful users obtain the same information about every message being exchanged in each phase. The idea is that by obtaining that information they can check and find deviations from the protocol and stop the protocol before the saboteur is able to break it. We will try to bring the users in a distributed system to an agreement on what messages each user has sent. By doing that we will induce the security of a protocol in a distributed system from its security in a round-table environment. Our exact goal is: "Given a round-table secure protocol P , produce a modified distributed protocol P' such that at every phase of P' which correspond to a phase of P there is an agreement about the messages sent in the previous phase of P , or at the first time that this does not hold, at least one faithful user holds a "proof" about the faultiness of some user".

Two types of distributed agreements have been discussed previously in the literature: Byzantine agreement and Crusader agreement. These two agreements will enable us to improve a round-table secure protocol. For the Crusader agreement let us assume that there exists a transmitter who is supposed to

send his value to the network and do so.

Crusader Agreement

- (1) If the transmitter is faulty, the value he has sent.
- (2) All the faithful users agree on the value the transmitter should send.

The elements of the agreement are that if all the faithful they reach agreement on the value the transmitter is introducing (the users do not necessarily all agree on the value). The agreement includes all the faithful users, the transmitter, and the saboteur. The transmitter should hold such a proof. All the faithful users should hold the value as the value of the transmitter.

In the following algorithm, the transmitter should contain the value of the transmitter.

The Crusader Algorithm

- C1. The transmitter notates the value.
- C2. If at the end of phase i , the transmitter is faulty, then notarize it at the end of phase i .
- C3. If at the end of phase i , the transmitter is faulty, then notarize it at the end of phase i .

Theorem 1:

If the cardinality of the set of faithful users reaches the threshold, the algorithm reaches the agreement.

The proof is similar to the proof of the Byzantine agreement. A faithful user can hold a proof about the faultiness of the transmitter. The transmitter is faulty. The transmitter is faulty. The transmitter is faulty.

Lemma 1:

A faithful user holds a proof about the faultiness of the transmitter. The transmitter is faulty. The transmitter is faulty. The transmitter is faulty.

The natural idea is to use the agreement about every message sent by the transmitter. The agreement among the faithful users is that at the end of the phase, the transmitter should hold the value of the transmitter.

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Crusader Agreement (Da)

- (1) If the transmitter is faithful, then all the faithful users should agree on the value he has sent.
- (2) All the faithful users who do not hold a "proof" of faultiness of the transmitter should agree on the same value.

The elements of the Crusader agreement are that as long as all users are faithful they reach agreement about every value being sent. When faultiness of the transmitter is introduced then the faithful users are divided into two sets (the users do not necessarily know who are the members of each set). One set includes all the faithful users holding a "proof" of the faultiness of the transmitter, and the second set is the set of all the faithful users who do not hold such a proof. All members of the second set should decide on the same value as the value of the transmitter.

In the following algorithm a notarized message carrying a value of the transmitter should contain also the transmitter's signature.

The Crusader Algorithm:

- C1. The transmitter notarizes his value at phase 1.
- C2. If at the end of phase 1 a single value signed by the transmitter is received, then notarize it at the next phase. Otherwise notarize the message "the transmitter is faulty".
- C3. If at the end of phase 2 at least 2 2-dense messages containing different values or at least $t+1$ signed messages saying that the transmitter is faulty are received define it to be a *proof of faultiness*. Otherwise agree on the only notarized value you have received.

Theorem 1:

If the cardinality of the set of faulty users is bounded by t , then the Crusader algorithm reaches the Crusader agreement at the end of phase 2.

The proof is similar to the proof in (Da). Observe that the proof of faultiness a faithful user can hold at the end of the algorithm is either two different values signed also by the transmitter or $t+1$ signed messages claiming that the transmitter is faulty. Neither of these can be produced unless the transmitter itself is faulty.

Lemma 1:

A faithful user holds a proof of faultiness only if the transmitter is faulty. If the transmitter is faithful, then no user (even a faulty one) can hold a proof of faultiness.

The natural idea is to run the algorithm to obtain the Crusader agreement about every message $T_k(u,v)$ being sent and by that to reach some sort of agreement among the faithful users about the various messages. The problem is that at the end of the Crusader agreement some of the faithful users do agree

on the message but some do not. So if those who did not find a "proof" of faultiness continue to follow the protocol they will send the next messages when the conditions about $M(k, u)$ do not hold.

We can obtain a round-table environment by running a Crusader agreement on every message and then adding another phase in which only users who hold a proof of faultiness will send it and the rest will wait a phase without doing anything. By doing this we ensure that every user who does not receive a proof of faultiness by the end of that phase can be sure that all the faithful users have obtained agreement on the value of the transmitter at the end of the Crusader agreement. Therefore if he continues that protocol he cannot cause any security problem because of the fact that the round-table conditions held at the previous phase.

If a faithful user obtains a proof of faultiness at the end of the Crusader algorithm, then by the end of the additional phase all the faithful users will learn about that. This will prevent them from continuing the protocol and will stop the protocol at that point without enabling the faulty users to break it.

Observe that it still may happen that some of the faithful users will see a proof of faultiness at the end of the additional phase and will stop taking part in the protocol because of that. This will bring about a situation in which not all the users have the same information. But in this case those that will continue will be covered because of the round-table condition and those that have stopped will try to stop the protocol before further phases will be completed.

To do this we actually need to run another algorithm that will distribute that proof of faultiness among the faithful users in order to bring them to an agreement about the faultiness of the transmitter. For that we use the Byzantine agreement. For the Byzantine agreement let's assume that users may hold a legal proof (of faultiness) and that every user can check its legality.

Byzantine Agreement (Da, DS, LSP, PSL)

- (1) If a faithful user holds a legal proof, then all the faithful users should agree on the existence of a legal proof.
- (2) All the faithful users should reach the same agreement.

The difference between the two agreements seems to be small but it is important. The Byzantine agreement requires reaching agreement no matter what. The Byzantine agreement requires more phases than the Crusader agreement. We will run it after completing the Crusader agreement in parallel with the rest of the protocol in such a way that if a fault has been found, the Byzantine agreement will broadcast it and will stop the rest of the protocol.

The Byzantine agreement will be used here to agree on the faultiness of some user. For this reason the version of the algorithm presented here will be optimized for this use.

The Byzantine Algorithm:

- B1. Every faithful user who holds a legal proof notarizes his proof at phase 1.

- B2. If at the end of phase k a user u has a legal proof of faultiness by a user who did not find a proof of faultiness in phase $k-1$ and agrees on the value of the transmitter at the end of phase $k-1$.
- B3. If by the end of phase k a user u has a legal proof of faultiness by a user who did not find a proof of faultiness in phase $k-1$ and agrees on the proof of faultiness by a user who did not find a proof of faultiness in phase $k-1$.

Theorem 2:

If the cardinality of the set of faithful users is n and the Byzantine agreement algorithm reaches the Byzantine agreement at phase $k < t+1$ some faithful users will have a legal proof of faultiness by phase $k+1$ all the faithful users will have a legal proof of faultiness by phase $k+1$.

The proof is similar to the proof of the definition of Byzantine agreement.

4. Algorithm for Improving the Security of the Byzantine Agreement

Let P be a given protocol. We will transform it into a protocol P' which is secure for a distributed system with n users and t faulty users. The phases of P' are the same as the phases of P , s.t. each phase of P' consists of a phase of P followed by a phase of the Byzantine agreement.

A proof of faultiness is a pair (a, b) such that:

- (1) it is about sending a message a at phase $3k-2$.
- (2) it contains either two faithful users u and v who both received a at that phase or a faithful user u who received a at that phase and a faithful user v who received b at that phase. $T_k(a, b)$ claiming no faultiness.
- (3) it is k -dense.
- (4) it is received by phase k .

The legality of a proof of faultiness is defined by the assumptions, by every user who receives a proof of faultiness then the receiving user will agree on the value of the transmitter at the end of phase k .

To simplify the algorithm we will assume that every user who receives a message a at phase $3k-2$ will agree on the value of the transmitter at the end of phase k if he receives a proof of faultiness by phase k .

Crusader-Byzantine Agreement

Define P' to be the protocol P followed by the Byzantine agreement.

- CB1. At phase $3k-2$: for every user u who receives a message a at phase $3k-2$, u will agree on the value of the transmitter at the end of phase k if he receives a proof of faultiness by phase k .
- CB2. At phase $3k$: If a user u has a legal proof of faultiness by a user who did not find a proof of faultiness in phase $k-1$ and agrees on the value of the transmitter at the end of phase $k-1$ and agrees on the proof of faultiness by a user who did not find a proof of faultiness in phase $k-1$.

The algorithm takes t phases to reach the Byzantine agreement. The algorithm takes t phases to reach the Byzantine agreement. The algorithm takes t phases to reach the Byzantine agreement.

to find a "proof" of faultiness in the next messages when the

reaching a Crusader agreement in which only users who hold a proof of faultiness at the end of phase t without doing anything are not receive a proof of faultiness. If all the faithful users have reached the end of the Crusader agreement, then the Byzantine cannot cause any security conditions held at the

the end of the Crusader agreement the faithful users will learn the Byzantine protocol and will stop the protocol to break it.

The faithful users will see a proof of faultiness and will stop taking part in the protocol in which not all the users that will continue will be able to see that have stopped will be completed.

The algorithm that will distribute the proof to bring them to an agreement that we use the Byzantine algorithm that users may hold a proof of its legality.

The faithful users should agree

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The number of phases to be small but it is not a Byzantine agreement no matter how many the Crusader agreement in parallel with the Byzantine algorithm. If a proof has been found, the Byzantine algorithm the protocol.

The algorithm on the faultiness of the proof presented here will be

his proof at phase 1.

B2. If at the end of phase $k < t+1$ a k -dense legal proof of faultiness is received by a user who did not notarize it before, then he notarizes it at the next phase and agrees on the proof of faultiness.

B3. If by the end of phase $t+1$ a $t+1$ -dense proof of faultiness is received, then all users agree on the proof of faultiness.

Theorem 2:

If the cardinality of the set of faulty users is bounded by t , then the Byzantine algorithm reaches the Byzantine agreement at the end of phase $t+1$. If at some phase $k < t+1$ some faithful user agrees on a legal proof of faultiness, then by phase $k+1$ all the faithful users will agree on a legal proof of faultiness.

The proof is similar to the proof in (DS) although our algorithm and definition of Byzantine agreement is somewhat different.

4. Algorithm for Improving Security

Let P be a given protocol. The following algorithm will show how to obtain from it a protocol P' with the property that if P is round-table secure, then P' is secure for a distributed system. Furthermore, P' will have three times as many phases as P , s.t. each phase k in P corresponds to phases $3k-2, 3k-1, 3k$ in P' .

A proof of faultiness is called legal if

- (1) it is about sending or not sending some $T_k(a,b)$ that had to be sent by a user at phase $3k-2$.
- (2) it contains either two different values being sent (and signed) by the faulty user a at that phase or $t+1$ signatures of users who are supposed to receive $T_k(a,b)$ claiming not to receive it at that phase.
- (3) it is k -dense.
- (4) it is received by phase $k' < 3k$ of P' .

The legality of a given proof of faultiness can be checked, due to our assumptions, by every user who receives it. If a proof of faultiness is not legal, then the receiving user can ignore it.

To simplify the arguments in the following algorithm we assume that every message a user has to send according to protocol P contains the name of the user who suppose to receive that message in P .

Crusader-Byzantine algorithm

Define P' to be the protocol obtained from P as follows: for every $k > 0$

CB1. At phase $3k-2$: for every faithful user u , if u did not agree on a legal proof of faultiness by now, then for every $T_k(u,v)$ that u is supposed to send according to the protocol P at phase k he uses the Crusader algorithm to send the message " $T_k(u,v)$, the phase is $3k-2$ ". (Recall that the Crusader algorithm takes two phases, $3k-2$ and $3k-1$).

CB2. At phase $3k$: If a faithful user u holds a proof of faultiness about some user b at phase $3k-2$, then he starts a Byzantine agreement to send that legal proof of faultiness to all the users. Otherwise, he defines $M(k,u) = M(k-1,u) \cup \{T_k(a,b) \mid u \text{ has agreed on at phase } 3k-1\}$.

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The algorithm we presented gives a way to induce security of distributed protocols from that of a round-table protocol. Thus, a protocol designer can concentrate on producing round-table secure protocols, and then convert them using our algorithm to be secure in a distributed system. Further research is needed for obtaining the most efficient way to transform nondistributed secure protocols to be secure in a distributed system.

The ideas presented in the paper can also be used for networks in which not every two users can communicate directly. In addition, the ideas can be used for improving protocols that are secure in environments fulfilling weaker assumptions than the round-table environment.

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